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Eyrie Press

In Search of the Self Eyrie Press,2011-10-20

Intelligent Robot Feng Duan,Wenyu Li,Ying Tan,2023-02-21 Today, the development of robots is making steady advances. In particular, the Robot Operating System (ROS) offers a unified platform that greatly facilitates the development of robots and has become a new hotspot for learning and application in the field of robotics research. This book introduces readers to the key technologies and development methods for ROS-based intelligent robots. Covering both the development history of robots and various aspects of programming robots, it offers effective support for beginners. The book is divided into three parts, the first of which introduces the basics of robots, including their definition, development, composition, and key technologies. In turn, the second part covers the hardware and software components and the implementation of functions such as vision, speech, grasping, and autonomous navigation. These functions need to work together to provide user-friendlier and more intelligent service. The third part shows how to develop robots with different functions in different application scenarios. Combining theoretical and practical aspects, with a strong focus on application, this work can be used as a reference book for robotics-related courses. Moreover, it will benefit all readers who are interested in intelligent robot development, sharing essential insights into developing service robots based on ROS.

The Coming Robot Revolution Yoseph Bar-Cohen,David Hanson,2009-04-20 Making a robot that looks and behaves like a human being has been the subject of many popular science fiction movies and books. Although the development of such a robot faces many challenges, the making of a virtual human has long been potentially possible. With recent advances in various key technologies related to hardware and software, the making of humanlike robots is increasingly becoming an engineering reality. Development of the required hardware that can perform humanlike functions in a lifelike manner has benefitted greatly from development in such technologies as biologically inspired materials, artificial intelligence, artificial vision, and many others. Producing a humanlike robot that makes body and facial expressions, communicates verbally using extensive vocabulary, and interprets speech with high accuracy is extremely complicated to engineer. Advances in voice recognition and speech synthesis are increasingly improving communication capabilities. In our daily life we encounter such innovations when we call the telephone operators of most companies today. As robotics technology continues to improve we are approaching the point where, on seeing such a robot, we will respond with “Wow, this robot looks unbelievably real!” just like the reaction to an artificial flower. The accelerating pace of advances in related fields suggests that the emergence of humanlike robots that become part of our daily life seems to be imminent. These robots are expected to raise ethical concerns and may also raise many complex questions related to their interaction with humans.

Powertrain Systems for Net-Zero Transport Institution of Mechanical Engineers (IME),2021-12-21 The transport sector continues to shift towards alternative powertrains, particularly with the UK Government’s announcement to end the sale of petrol and diesel passenger cars by 2030 and increasing support for alternatives. Despite this announcement, the internal combustion continues to play a significant role both in the passenger car market through the use of hybrids and sustainable low carbon fuels, as well as a key role in other sectors such as heavy-duty vehicles and off-highway applications across the globe. Building on the industry-leading IC Engines conference, the 2021 Powertrain Systems for Net-Zero Transport conference (7-8 December 2021, London, UK) focussed on the internal combustion engine’s role in Net-Zero transport as well as covered developments in the wide range of propulsion systems available (electric, fuel cell, sustainable fuels etc) and their associated powertrains. To achieve the net-zero transport across the globe, the life-cycle analysis of future powertrain and energy was also discussed. Powertrain Systems for Net-Zero Transport provided a forum for engine, fuels, e-machine, fuel cell and powertrain experts to look closely at developments in powertrain technology required, to meet the demands of the net-zero future and global competition in all sectors of the road transportation, off-highway and stationary power industries.

The Other British Isles David W. Moore,2011-01-04 Their names bespeak a rich past. From the Norse Hjaltland comes the modern Shetland: islands nominally Scottish, steeped in Nordic culture, closer to the Arctic Circle than to London. Important Neolithic sites are at Skara Brae and Maes Howe in the Orkneys. Holy Iona, island center of Celtic Christianity, the Isle of Man, former seat of rule over the Irish Sea, and Anglesey and Islay, homes of medieval courts at Aberffraw and Loch Finlaggan, are just a few of the more than 6,000 islands that form the archipelago known as the British Isles. The offshore isles are home to half a million people. Focusing on the eight islands or chains that have long supported substantial populations, this history tells the stories of Shetland, Orkney, the Hebrides, Anglesey, the Channel Islands, the Scilly Isles, and the Isles of Man and Wight, from their Neolithic settlement, to Roman, Norse and Norman occupation, to the struggle to maintain their uniqueness in today's world. Instructors considering this book for use in a course may request an examination copy here.

Nexi Robot, The Toney Allman,2009-07-15 Nexi is one of a team of four small humanoid robots that have mobility, dexterity and social communication skills. Every great invention begins with a great idea! Read all the books in this series and learn about the history and impact of some of the most fascinating innovations and inventions of our time. Explore the idea’s early stages of development, problems encountered along the way, and how each great idea has influenced our lives. From popular culture and the environment to life-saving machines, learn about the ideas, people, and technologies that made it all happen. This series correlates with The Science, Technology, Engineering, and Math (S.T.E.M.) curriculum initiative.

Parallel Robots J.-P. Merlet,2012-12-06 Parallel robots are closed-loop mechanisms presenting very good performances in terms of accuracy, rigidity and ability to manipulate large loads. Parallel robots have been used in a large number of applications ranging from astronomy to flight simulators and are becoming increasingly popular in the field of machine-tool industry. This book presents a complete synthesis of the latest results on the possible mechanical architectures, analysis and synthesis of this type of mechanism. It is intended to be used by students (with over 100 exercises and numerous Internet addresses), researchers (with over 500 references and anonymous ftp access to the code of some algorithms presented in this book) and engineers (for which practical results and applications are presented).

Robot Technology Ian Graham,2010-05 Robot Technology looks at robots that are used in space exploration, and developments that may happen in the future, for example, landing on Mars. It looks at robot explorers that go to places humans cannot reach, such as the sea bed, and into the craters of volcanoes. The title explores military machines, and discusses the possibility of humanoid robots. It also asks important questions about whether advances in robot technology could threaten humans. New Technology is an exciting, up-to-date look at new technology and the effect it is having on the world. Each title looks forward to likely future technological advances that will affect our everyday lives.

Information Arts Stephen Wilson,2003-02-28 An introduction to the work and ideas of artists who use—and even influence—science and technology. A new breed of contemporary artist engages science and technology—not just to adopt the vocabulary and gizmos, but to explore and comment on the content, agendas, and possibilities. Indeed, proposes Stephen Wilson, the role of the artist is not only to interpret and to spread scientific knowledge, but to be an active partner in determining the direction of research. Years ago, C. P. Snow wrote about the two cultures of science and the humanities; these developments may finally help to change the outlook of those who view science and technology as separate from the general culture. In this rich compendium, Wilson offers the first comprehensive survey of international artists who incorporate concepts and research from mathematics, the physical sciences, biology, kinetics, telecommunications, and experimental digital

systems such as artificial intelligence and ubiquitous computing. In addition to visual documentation and statements by the artists, Wilson examines relevant art-theoretical writings and explores emerging scientific and technological research likely to be culturally significant in the future. He also provides lists of resources including organizations, publications, conferences, museums, research centers, and Web sites.

Robert Johnson, Mythmaking, and Contemporary American Culture Patricia R. Schroeder, 2004-06-14 Suddenly Robert Johnson is everywhere. Though the Mississippi bluesman died young and recorded only twenty-nine songs, the legacy, legend, and lore surrounding him continue to grow. Focusing on these developments, Patricia R. Schroeder's *Robert Johnson, Mythmaking, and Contemporary American Culture* breaks new ground in Johnson scholarship, going beyond simple or speculative biography to explore him in his larger role as a contemporary cultural icon. Part literary analysis, part cultural criticism, and part biographical study, *Robert Johnson, Mythmaking, and Contemporary American Culture* shows the Robert Johnson of today to be less a two-dimensional character fixed by the few known facts of his life than a dynamic and contested set of ideas. Represented in novels, in plays, and even on a postage stamp, he provides inspiration for highbrow cultural artifacts--such as poems--as well as Hollywood movies and T-shirts. Schroeder's detailed and scholarly analysis directly engages key images and stories about Johnson (such as the Faustian crossroads exchange of his soul for guitar virtuosity), navigating the many competing interpretations that swirl around him to reveal the cultural purposes these stories and their tellers serve. Unprecedented in both range and depth, Schroeder's work is a fascinating examination of the relationships among Johnson's life, its subsequent portrayals, and the cultural forces that drove these representations. With penetrating insights into both Johnson and the society that perpetuates him, *Robert Johnson, Mythmaking, and Contemporary American Culture* is essential reading for cultural critics and blues fans alike.

Introduction to Mobile Robot Control Spyros G Tzafestas, 2013-10-03 *Introduction to Mobile Robot Control* provides a complete and concise study of modeling, control, and navigation methods for wheeled non-holonomic and omnidirectional mobile robots and manipulators. The book begins with a study of mobile robot drives and corresponding kinematic and dynamic models, and discusses the sensors used in mobile robotics. It then examines a variety of model-based, model-free, and vision-based controllers with unified proof of their stabilization and tracking performance, also addressing the problems of path, motion, and task planning, along with localization and mapping topics. The book provides a host of experimental results, a conceptual overview of systemic and software mobile robot control architectures, and a tour of the use of wheeled mobile robots and manipulators in industry and society. *Introduction to Mobile Robot Control* is an essential reference, and is also a textbook suitable as a supplement for many university robotics courses. It is accessible to all and can be used as a reference for professionals and researchers in the mobile robotics field. Clearly and authoritatively presents mobile robot concepts Richly illustrated throughout with figures and examples Key concepts demonstrated with a host of experimental and simulation examples No prior knowledge of the subject is required; each chapter commences with an introduction and background

Biomimetics Yoseph Bar-Cohen, 2016-04-19 Mimicking nature - from science fiction to engineering reality Humans have always looked to nature's inventions as a source of inspiration. The observation of flying birds and insects leads to innovations in aeronautics. Collision avoidance sensors mimic the whiskers of rodents. Optimization algorithms are based on survival of the fittest, the seed-

Human-Robot Interactions in Future Military Operations Florian Jentsch, 2016-05-23 Soldier-robot teams will be an important component of future battle spaces, creating a complex but potentially more survivable and effective combat force. The complexity of the battlefield of the future presents its own problems. The variety of robotic systems and the almost infinite number of possible military missions create a dilemma for researchers who wish to predict human-robot interactions (HRI) performance in future environments. *Human-Robot Interactions in Future Military Operations* provides an opportunity for scientists investigating military issues related to HRI to present their results cohesively within a single volume. The issues range from operators interacting with small ground robots and aerial vehicles to supervising large, near-autonomous vehicles capable of intelligent battlefield behaviors. The ability of the human to 'team' with intelligent unmanned systems in such environments is the focus of the volume. As such, chapters are written by recognized leaders within their disciplines and they discuss their research in the context of a broad-based approach. Therefore the book allows researchers from differing disciplines to be brought up to date on both theoretical and methodological issues surrounding human-robot interaction in military environments. The overall objective of this volume is to illuminate the challenges and potential solutions for military HRI through discussion of the many approaches that have been utilized in order to converge on a better understanding of this relatively complex concept. It should be noted that many of these issues will generalize to civilian applications as robotic technology matures. An important outcome is the focus on developing general human-robot teaming principles and guidelines to help both the human factors design and training community develop a better understanding of this nascent but revolutionary technology. Much of the research within the book is based on the Human Research and Engineering Directorate (HRED), U.S. Army Research Laboratory (ARL) 5-year Army Technology Objective (ATO) research program. The program addressed HRI and teaming for both aerial and ground robotic assets in conjunction with the U.S. Army Tank and Automotive Research and Development Center (TARDEC) and the Aviation and Missile Development Center (AMRDEC) The purpose of the program was to understand HRI issues in order to develop and evaluate technologies to improve HRI battlefield performance for Future Combat Systems (FCS). The work within this volume goes beyond the research results to encapsulate the ATO's findings and discuss them in a broader context in order to understand both their military and civilian implications. For this reason, scientists conducting related research have contributed additional chapters to widen the scope of the original research boundaries.

Using Computer Science in Military Service Xina M. Uhl, 2018-12-15 Computers play an integral role in the military's primary goal, defending the nation and its interests, and will continue to do so in the foreseeable future. Opportunities for computer science coding careers abound in weapons design, advanced robotics, artificial intelligence, sophisticated drones, and the ever-evolving, and ever-important field of cyber warfare. This compelling, extensive book provides solid career guidance specific to the military's organization. It offers ideas for employment with civilian organizations that serve the armed forces' technology needs. It is perfect for readers who are considering both full-time and part-time service, whether for an entire career or limited tours of duty.

Robots Are People Too John Frank Weaver, 2013-11-26 The only book of its kind to look at how our legal system needs to change to accommodate a world in which machines, in addition to people, make decisions. For years, robots were solely a matter of science fiction. Today, artificial intelligence technologies serve to accelerate our already fast-paced lives even further. From Apple's Siri to the Google Car to GPS, machines and technologies that make decisions and take action without direct human supervision have become commonplace in our daily lives. As a result, laws must be amended to protect companies that produce robots and the people that buy and use them. This book provides an extensive examination of how numerous legal areas—including liability, traffic, zoning, and international and constitutional law—must adapt to the widespread use of artificial intelligence in nearly every area of our society. The author scrutinizes the laws governing such fields as transportation, medicine, law enforcement, childcare, and real estate development.

Modern Robotics Harry Henderson, 2006 Profiles eleven notable scientists in the field of robotics, discussing their research, accomplishments, ethical and professional obstacles, and contributions.

Includes photographs, illustrations, chronology of notable events, and a list of resources.

Textbook of Neural Repair and Rehabilitation: Volume 2, Medical Neurorehabilitation Michael Selzer,Stephanie Clarke,Leonardo Cohen,Gert Kwakkel,Robert Miller,2014-04-24 In two freestanding volumes, Textbook of Neural Repair and Rehabilitation provides comprehensive coverage of the science and practice of neurological rehabilitation. Revised throughout, bringing the book fully up to date, this volume, Medical Neurorehabilitation, can stand alone as a clinical handbook for neurorehabilitation. It covers the practical applications of the basic science principles presented in Volume 1, provides authoritative guidelines on the management of disabling symptoms, and describes comprehensive rehabilitation approaches for the major categories of disabling neurological disorders. New chapters have been added covering genetics in neurorehabilitation, the rehabilitation team and the economics of neurological rehabilitation, and brain stimulation, along with numerous others. Emphasizing the integration of basic and clinical knowledge, this book and its companion are edited and written by leading international authorities. Together they are an essential resource for neuroscientists and provide a foundation of the work of clinical neurorehabilitation professionals.

Textbook of Neural Repair and Rehabilitation Michael E. Selzer,Stephanie Clarke,Leonardo G. Cohen,Gert Kwakkel,Robert H. Miller,2014-04-24 Volume 2 of the Textbook of Neural Repair and Rehabilitation stands alone as a clinical handbook for neurorehabilitation.

Intelligent Planning for Mobile Robotics: Algorithmic Approaches Tiwari, Ritu,2012-09-30 Robotics is an ever-expanding field and intelligent planning continues to play a major role. Given that the intention of mobile robots is to carry out tasks independent from human aid, robot intelligence is needed to make and plan out decisions based on various sensors. Planning is the fundamental activity that implements this intelligence into the mobile robots to complete such tasks. Understanding problems, challenges, and solutions to path planning and how it fits in is important to the realm of robotics. Intelligent Planning for Mobile Robotics: Algorithmic Approaches presents content coverage on the basics of artificial intelligence, search problems, and soft computing approaches. This collection of research provides insight on both robotics and basic algorithms and could serve as a reference book for courses related to robotics, special topics in AI, planning, applied soft computing, applied AI, and applied evolutionary computing. It is an ideal choice for research students, scholars, and professors alike.

Gareth's Guide to Building a Robot Therese M. Shea,2018-07-15 An exploration of robotics has never been timelier. In schools, students sign up for robotics clubs and competitions. More and more robotics technology is being introduced in the workplace. Many people are wondering what the future relationship between robots and humans will be. Readers might think building a robot, or becoming the kind of engineer who does, is out of reach. They couldn't be more wrong! This carefully researched volume explains the parts of a robot, how it functions, and its many uses in our world today. It's sure to inspire an appreciation for robotics and the technology of today, and tomorrow.

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